Influence of Freestream Values on $k-\omega$ Turbulence Model Predictions

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Introduction

T WO equation eddy-viscosity turbulence models are among the most widely used models today. The most popular is the $k - \epsilon$ model in one of its many different forms. However, a significant number of alternative models have been developed, both for physical and for numerical reasons. Those models are designed to overcome some of the well-known shortcomings of the $k - \epsilon$ model.

One of the more successful of the alternative models is the $k-\omega$ model developed by Wilcox.^{1,2} It has the advantage that it does not require damping functions in the viscous sublayer and that the equations are less stiff near the wall. Furthermore, it has been designed to predict the proper wake strength in equilibrium adverse pressure gradient boundary-layer flows.

Very encouraging results for a variety of wall-bounded flows have been reported by different authors.¹⁻³ However, when applied to free shear layers, a strong dependency of the results on the freestream value of ω has been found.² To investigate this disturbing feature of the equations more closely, the self-similar equations for incompressible equilibrium boundary layers, as well as for the far wake, have been solved numerically. Different freestream values ω_f have been specified to determine its influence on the solution. From the self-similar equations one can also get estimates for acceptable values of ω_f . To show that the solution dependency of ω_f is not simply a property of the self-similar equations, Navier-Stokes computations have been performed for a flat plate boundary layer that confirm the results.

Defect Layer and Far Wake Analysis

Wilcox has performed a defect layer analysis for the $k-\omega$ model to investigate the model performance for equilibrium boundary-layer flows. The analysis is based on a singular perturbation solution with respect to the (small) ratio of the friction velocity to the boundary-layer edge velocity u_r/U_e . It is further assumed that the Reynolds number based on displacement thickness is high, $Re_{\delta^*} \rightarrow \infty$. The equations prescribing the self-similar far wake flow are identical to the equations derived by Wilcox, if u_{τ} is replaced by $u_1 = U_e \sqrt{\delta^*/x}$. The details of the analysis can be found in Ref. 1, and therefore only a brief summary of the equations is given here. The defect layer and far wake equations are as follows:

$$\frac{\partial}{\partial \eta} \left[N_0 \frac{\partial U_1}{\partial \eta} \right] + (\alpha_T - 2\beta_T - 2\omega_T)\eta \frac{\partial U_1}{\partial \eta} + (\beta_T - 2\omega_T)U_1 = 0$$

$$\sigma^* \frac{\partial}{\partial \eta} \left[N_0 \frac{\partial K_0}{\partial \eta} \right] + (\alpha_T - 2\beta_T - 2\omega_T)\eta \frac{\partial K_0}{\partial \eta} - 4\omega_T K_0$$

$$+ \sqrt{\beta^*} \left[N_0 \left(\frac{\partial U_1}{\partial \eta} \right)^2 - K_0 W_0 \right] = 0$$

$$\sigma \frac{\partial}{\partial \eta} \left[N_0 \frac{\partial W_0}{\partial \eta} \right] + (\alpha_T - 2\beta_T - 2\omega_T)\eta \frac{\partial W_0}{\partial \eta}$$

$$+ (\alpha_T - \beta_T - 4\omega_T) W_0 + \sqrt{\beta^*} \left[\gamma \left(\frac{\partial U_1}{\partial \eta} \right)^2 - \frac{\beta}{\beta^*} W_0^2 \right] = 0$$
(1)

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where U_1 , K_0 , and W_0 are the nondimensional defect velocity, turbulent kinetic energy, and turbulent dissipation rate ω , respectively. N_0 is the dimensionless eddy viscosity:

$$N_0 = \frac{\nu_t}{U_e \delta^*} = \frac{K_0}{W_0}$$
 (2)

whereas α_T , β_T , and ω_T are defined as follows:

$$\alpha_T = \frac{2}{C_f} \frac{\mathrm{d}\delta^*}{\mathrm{d}x} , \quad \beta_T = \frac{\delta^*}{\tau_w} \frac{\mathrm{d}p}{\mathrm{d}x} , \quad \omega_T = \frac{\delta^*}{C_f u_\tau} \frac{\mathrm{d}u_\tau}{\mathrm{d}x}$$
(3)

where δ^* is the displacement thickness, τ_w is the wall shear stress, and $C_f/2 = (u_\tau/U_e)^2$. The values of these quantities for a zero pressure gradient boundary layer are $\alpha_T = 1$, $\beta_T = 0$, and $\omega_T = 0$. For the wake flow, they are: $\alpha_T = 0$, $\beta_T = 0$, $\omega_T = -0.25$. The constants in the k- ω model are

$$\beta = 3/40, \ \beta^* = 0.09, \ \kappa = 0.41, \ \gamma = 5/9, \ \sigma = 0.5, \ \sigma^* = 0.5$$
 (4)

For boundary-layer applications, the equations must be matched to the law of the wall,¹ whereas symmetry conditions are imposed on the wake centerline. At the outer boundary $\eta \rightarrow \infty$, all three quantities are assigned small values:

$$U_1 = 0, \quad K_0 = K_f, \quad W_0 = W_f$$
 (5)

The equations are solved with a first-order upwind scheme for the convection terms $\eta(\partial/\partial\eta)$ and central differencing for the other derivatives. Following Wilcox,¹ time derivatives are added to integrate the equations. Highly accurate numerical results were obtained by using up to 500 gridpoints in η . Grid independency was reached with about 100 gridpoints inside the layer.

Results

The equations have been solved with different freestream values W_f specified. Note that the W_0 equation has two different algebraic solutions in the freestream that are compatible with the equilibrium assumption. One is $W_f = 0$ and the second is

$$W_f = : W_a = (\alpha_T - \beta_T - 4\omega_T) \frac{\sqrt{\beta^*}}{\beta}$$
(6)

Although intermediate values are not strictly compatible with the equilibrium assumptions, they will be included to show the changes of the solution as W_f approaches zero (setting W_f exactly to zero is not possible for numerical reasons).

Computations show that specification of values for W_f larger than W_a does not influence the results, as W_0 falls to W_a at the boundary-layer edge before approaching $W_f > W_a$ outside the boundary layer. However, specifying smaller values has a pronounced influence. Computations have been performed with

$$W_f = W_a \cdot 10^{-n}, \qquad n = 0, 1, 2, \dots$$
 (7)

The value of K_f was changed in a way to keep the freestream value of the eddy viscosity at a low value of $N_f = 10^{-4}$ (changes in N_f do not affect the solution, as long as it is small compared with the values of N_0 inside the boundary layer). Figure 1 shows the results for the equilibrium boundary-layer computations. The influence of W_f on the solution can be seen most dramatically with regard to the eddy viscosity N_0 . N_0 increases as W_f decreases and does not go to zero at the boundary-layer edge $\delta_{0.995}$. The influence on the mean flow profile $U_1(\eta)$ is moderate, and that is the reason why the freestream dependency is of little consequence for boundarylayer flows. However, near the boundary-layer edge the solution changes from a profile with a sharply defined boundary-

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Fig. 1 Solutions of the defect layer equations with different freestream values for W_0 , $W_f = W_a 10^{-n}$, n = 0, 1, 2, 3, ...



Fig. 2 Solutions of the far wake equations with different freestream values for W_0 , $W_f = W_a 10^{-n}$, $n = 0, 1, 2, 3, \ldots$

layer edge, to one that approaches the freestream values asymtotically as W_f decreases.

Figure 2 shows the solution for wake flows. The changes in N_0 are similar to the ones for the boundary-layer computations, only now the whole shear layer is affected because of the missing wall influence. The velocity profile is also strongly affected and shows a much larger spreading rate as W_f decreases. Again the sharp edge of the shear layer is lost, and all variables approach their freestream values asymptotically.

Analysis of the defect layer equations shows^{4,5} that two equation models generally produce solutions with a sharp boundary-layer edge (discontinuous in the first derivatives). This is also true for the design solution of the $k \cdot \omega$ model if $W_f = W_a$. However, for the limiting case $K_f = 0$ and $W_f = 0$, no such solution exists and the solution for large η becomes

$$U_1 = C_1 e^{-\lambda \eta^2}$$

$$K_0 = C_2 e^{-\lambda^* \eta^2}$$

$$W_0 = C_3 e^{-\lambda^* \eta^2}$$
(8)

The exponents are

$$\lambda = (\alpha_T - 2\beta_T - 2\omega_T)/(2N_0)$$
$$\lambda^* = (\alpha_T - 2\beta_T - 2\omega_T)/[2N_0\sigma^{(*)}]$$
(9)

Since σ is equal to σ^* , K_0 and W_0 decay in the same manner, allowing for a constant eddy viscosity $N_0 = C_2/C_3$ (see Fig. 2). Note that the previous solution exists only if $\sigma = \sigma^*$. If σ is not equal to σ^* , the solution has a sharp boundary-layer edge, but a strong dependency of ω_f remains.

Computations with the $k - \epsilon$ model for the previous cases show almost no dependency on the freestream values. As pointed out in Refs. 1 and 6, the main difference between both models is a term of the form

$$2(\nu + \sigma \nu_t) \frac{1}{k} \frac{\partial k}{\partial x_i} \frac{\partial \omega}{\partial x_i}$$
(10)

that is not included in the ω equation (note that an additional diffusion term appears if the diffusion constants are not equal). In the self-similar limit, the expression in Eq. (10) becomes

$$2\sigma N_0 \frac{1}{K_0} \frac{\mathrm{d}K_0}{\mathrm{d}\eta} \frac{\mathrm{d}W_0}{\mathrm{d}\eta} \tag{11}$$

and has to be added to the left-hand side of the W_0 equation.

Figure 3 shows computations for the wake flow with this term included in the k- ω model. The main difference is that the influence of W_f does not penetrate into the boundary layer. The freestream dependency is thereby avoided. The computations shown in Fig. 3 have been performed with the constants of the Jones-Launder k- ϵ model transformed to the k- ω model (the freestream dependency is also removed if the original constants are used).

The inclusion of the term in Eq. (10), however, is not desirable because it makes the $k - \omega$ model formally identical to the $k - \epsilon$ model and thereby destroys the advantages of the model in the near wall region and for adverse pressure gradient boundary layers.

The argument can be made that the previous findings are specific features of the self-similar equations and do not appear if the full equations are solved. To investigate this point, flat plate boundary-layer computations based on the incompressible Reynolds-averaged Navier-Stokes equations have been performed. The freestream value ω_f at the inflow boundary was reduced to small values (note that the freestream value of k was also reduced to keep the eddy viscosity in the freestream small). The results are almost identical to the ones shown in Fig. 1, thus providing further evidence that the similarity solutions capture the essence of the problem.

The present results show that it is very important to specify ω_f appropriately at the inflow boundary. In cases where the freestream values inside the computational domain cannot be



Fig. 3 Solutions of the far wake equations with different freestream values for W_0 , $W_f = W_a 10^{-n}$, $n = 0, 1, 2, 3, \ldots, 2\sigma N_0(1/K_0)$ (d $K_0/d\eta$) (d $W_0/d\eta$) is included in the W_0 equation.

sufficiently controlled by the inflow conditions alone, it may be even necessary to impose a lower limit on ω . Estimates for those values can be obtained from the definition of W_0 (Ref. 1) and from Eq. (6):

$$\omega = \frac{u_{\tau}^{2}}{\sqrt{\beta^{*}}U_{e}\delta^{*}} W_{0}(\eta)$$

$$\omega_{a} = \frac{1}{\beta} \frac{u_{\tau}^{2}}{U_{e}\delta^{*}} (\alpha_{T} - \beta_{T} - 4\omega_{T})$$
(12)

For high Reynolds number boundary-layer flows, this gives the following estimate:

$$\omega_a = \frac{1}{\beta} \frac{1}{\delta^*} \frac{\mathrm{d}}{\mathrm{d}x} \left(U_e \delta^* \right) = \mathcal{O}\left(10 \frac{U_\infty}{L} \right)$$
(13)

where U_{∞} is the freestream velocity and L is a characteristic length in the streamwise direction. In high Reynolds number boundary-layer applications, these rather large values can be specified because ω inside the layer in still several orders of magnitude larger and ω_f is therefore relatively small. It is the author's experience that the freestream dependency is no major problem in boundary-layer computations and can be avoided by specifying appropriate inflow conditions and/or lower limits on ω .

The problem is more severe in free shear layer applications in which case the freestream value W_a is of the same order as W_0 (see Fig. 2) inside the layer, and therefore it is not appropriate to impose a lower limit. The inclusion of additional terms in the ω equation or changes in the expression for the eddy viscosity might be necessary to ensure solutions that are both insensitive to ω_f and consistent with experiments.

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Stability of Plane Nonorthogonal Stagnation Flow

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I. Introduction

T HE problem of stability of stagnation flow is of continuous interest in aerospace applications mainly because this flow well approximates flows around leading edges of airfoils. It is widely believed that this flow is linearly stable.¹ Recent

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numerical simulations of Spalart² show this flow to be also nonlinearly stable. Experiments³ demonstrate close coupling between the form of the oncoming disturbances and the secondary flow observed in the stagnation region; however, the mechanism of this coupling is not completely understood. Certain aspects of this coupling can be explained on the basis of the "vorticity amplification theory."⁴ Possible roles of surface roughness have been discussed in Ref. 5. It is likely that the flow realized in experiments is nonorthogonal, or perhaps disturbances swept toward the body produce instantaneous nonorthogonality, which is sufficient to trigger the secondary flow. The objective of the present analysis is, therefore, to determine stability characteristics of such a nonorthogonal flow.

II. Analysis

We consider motion of a viscous fluid impinging obliquely on an infinite flat rigid wall. The geometry of the flow and the coordinate system are indicated in Fig. 1. The wall is in the (x, z) plane, and the mean flow is two dimensional in the (x, y)plane. The oncoming flow has the form

$$u^* = ax^* + 2aHy^*, \quad v^* = -ay^*$$
 (1)

i.e., it consists of a superposition of an irrotational stagnation-point flow and a uniform shear parallel to the wall with constant z component of vorticity ($\omega_z = 2H$). In the previous equation, u and v denote velocity components in the (x, y)directions, asterisks denote dimensional quantities, and a and H are scale constants. The angle of inclination of the flow with respect to the wall is $\beta = \arctan H^{-1}$.

We are interested in the character of the flow in the viscous layer next to the rigid wall when the far-field approximation is given by Eq. (1). This problem has been studied in Refs. 6–8. The following presentation is limited to a short outline.

Boundary-layer thickness δ , upstream velocity V_{∞} , and dynamic pressure ρV_{∞}^2 associated with the orthogonal stagnationpoint flow are selected as the length, velocity, and pressure scales, respectively. Here, $\delta = (\nu/a)^{1/2}$ where ν denotes kinematic viscosity and ρ stands for density. The Reynolds number is defined as $Re = V_{\infty}\delta/\nu$. Flow quantities are expressed as

$$U(x, y) = 1/Re \left[x U_0(y) + H U_1(y) \right], \quad V(x, y) = 1/Re V_0(y)$$
$$P_0 - P(x, y) = 1/Re^2 \left[\frac{1}{2}x^2 + G_0(y) \right] \tag{2}$$

where U and V are the mean flow velocity components in the (x, y) directions, P denotes the mean flow pressure, and $P_0 = P(0, 0)$. If we define

$$U_0 = \frac{\mathrm{d}F}{\mathrm{d}y}, \qquad V_0 = -F \tag{3}$$

and substitute Eqs. (2) and (3) into the incompressible Navier-Stokes and continuity equations, we find that F, G_0 , and U_1 must satisfy

$$\frac{\mathrm{d}^3 F}{\mathrm{d}y^3} + F \frac{\mathrm{d}^2 F}{\mathrm{d}y^2} - \left(\frac{\mathrm{d}F}{\mathrm{d}y}\right)^2 + 1 = 0 \tag{4a}$$

$$G_0 = \frac{\mathrm{d}F}{\mathrm{d}y} + \frac{1}{2}F^2 \tag{4b}$$

$$\frac{d^2 U_1}{dy^2} + F \frac{d U_1}{dy} - \frac{dF}{dy} U_1 = 0$$
 (4c)

$$F = \frac{\mathrm{d}F}{\mathrm{d}y} = U_1 = 0 \quad \text{at } y = 0 \tag{4d}$$

$$\frac{\mathrm{d}F}{\mathrm{d}y} \to 1, \qquad U_1 \to 2Y \quad \text{as } y \to \infty$$
 (4e)

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